

EinScan HX User Manual



V1.2.0.4

SHINING 3D[®]

Introduction

Thank you for purchasing the EinScan H series 3D Scanner.

EinScan HX is new developed handheld 3d scanner by Shining 3D. Based on combined structure light technology of LED and laser. EinScan HX is with unique performance of scanning common objects as most handheld structure light 3d scanners can at a fast-scanning speed with color texture, and also capable of scanning black and shiny objects that only laser 3d scanning are good at for a better accuracy.



If you need any support for your 3d scanner, please contact your local reseller or the EinScan support team einscan_support@shining3d.com.

Information in this document is subject to change without notice.

Note:

The manual provides important information of the proper operation of the product. Read before use.

Caution:

- Handle the scanner with care. Bumping or dropping off may cause the electronic and optical parts being damaged.
- EinScan HX uses a class I laser when using laser scan mode, which is eye and skin safe under all conditions of normal use, but long time staring at the laser beam directly is not suggested. Please avoid direct eye contact with the laser beam. Keep the laser beam away from children.
- Do not touch the camera lens.

Table of Contents

1. Spe	cification and System Requirements	1
1.1.	System Requirements	1
1.2. 1.2. 1.2. 1.2.	2. Scanner Body	2 3
	tware Set Up	
2.1.	Download the Software	
2.2.	Install the Software	
2.3.	Firmware Update	5
2.4.	Device Activation	6
2.5.	Software Update	7
2.6. 2.6. 2.6.	0	8
2.6		
2.6. 2.6.		
2.6	6. Alerts	11
3. Sof	ware Scan Workflow	13
4. Cali	bration	14
4.1.	Precautions and Use	14
4.2.	Preparation for Calibration	14
4.3.	How to Calibrate	15
5. Bef	ore Scanning	
		19
5.1.	Scanner Buttons	
5.1. 5.2.	-	19
5.2. 5.3.	Scanner Buttons Scan Modes Preparation	19 19 20
5.2.	Scanner Buttons Scan Modes Preparation 1. Rapid Scan	19 19 20 20
5.2. 5.3. 5.3. 5.3.	Scanner Buttons Scan Modes Preparation 1. Rapid Scan	19
5.2. 5.3. 5.3. 5.3.	Scanner Buttons Scan Modes Preparation 1. Rapid Scan 2. Laser Scan	19 20 20 20 22
5.2. 5.3. 5.3. 5.3. 6. Pro	Scanner Buttons Scan Modes Preparation 1. Rapid Scan 2. Laser Scan	19 20 20 20 22 22
5.2. 5.3. 5.3. 5.3. 6. Pro 6.1.	Scanner Buttons Scan Modes Preparation 1. Rapid Scan 2. Laser Scan ject New Project Group	19 20 20 20 22 22 22
5.2. 5.3. 5.3. 6. Pro 6.1. 6.2. 6.3. 6.3.	Scanner Buttons Scan Modes Preparation 1. Rapid Scan 2. Laser Scan ject New Project Group Open Project Group Pre-setting 1. Select Texture	19 20 20 20 20 22 22 22 22
5.2. 5.3. 5.3. 6. Pro 6.1. 6.2. 6.3. 6.3. 6.3.	Scanner Buttons Scan Modes Preparation 1. Rapid Scan 2. Laser Scan ject New Project Group Open Project Group Pre-setting 1. Select Texture 2. Alignments	19 20 20 20 22 22 22 22 22 22 22 22
5.2. 5.3. 5.3. 6. Pro 6.1. 6.2. 6.3. 6.3.	Scanner Buttons Scan Modes Preparation 1. Rapid Scan 2. Laser Scan ject New Project Group Open Project Group Pre-setting 1. Select Texture 2. Alignments 3. Resolution	19 20 20 20 22 22 22 22 22 22 23 24

	6.4.1. 6.4.2. 6.4.3.	Optimal Distance Range	26
	6.4.3. 6.4.4.		
7.			
		review	
		tart/Pause/Continue/Stop Scanning	
		lesume Scanning After Tracking Lost	
		Generate Point Clouds	
-		Clouds Editing	
		light-click Context Menu	
		Cutting Plane	
		-	
8.		ct Group	
		Create/Import Projects	
		emove/Delete Projects	
		lign Projects	
9.		ing	
9	.1. C 9.1.1.	reate Mesh (Watertight/Unwater tight) Mesh	
	9.1.2.		
9	.2. N	Лesh Editing	38
9	.3. т	exture Adjustment	39
9	.4. S	implification	40
9	.5. N	Nesh Optimization	40
9	.6. S	mooth	41
9	.7. R	emove Small Floating Parts	42
9	.8. A	uto Hole Filling	42
9	.9. N	Aanual Hole Filling	43
9	.10. T	exture Remapping	44
10.	Me	asurement	45
	10.3.1		
	10.3.2 10.3.3		
11.	Ехр	ort Data	
		Data Formats	
_		cale Data	
12.		re Data	
13.		rd-party Software	
14.		del Preview	

15.	Device Button	55
16.	Support and Contact	56
16.1	I. Submit a Ticket	56
16.2	2. Contact Us	57

1. Specification and System Requirements

1.1. System Requirements

Preparing a suitable computer will improve your scanning experience.

One important notice for PC configuration is the **graphic card**. It has to be **Nvidia card** since certain functions from Nvidia are needed for scanning. **GTX series card** is the best for scanning while Quadro series CAD card also works but you need a more expensive model comparing to the GTX series to get a good scan experience.

Components	Recommended Configurations	
Graphics card	NVIDIA GTX serial cards higher than GTX1080	
USB port	1 of 3.0 port	
OS	Win10 64 bits	
Video memory	> 8G	
RAM	32 GB	
CPU	i7-8700 or higher	
Screen resolution	1920 × 1080, DPI: 100%; 125% 3840 × 2106, DPI: 100%; 200%	

Recommended PC configurations:

Models	Configurations
Dell G3 laptop	Core i7-9750H, NVIDIA GeForce RTX 2060 6GB GDDR6, 2x8GB, DDR4,
	2666MHz
Asus ZenBook flip	Core i7, Nvidia MX250 with 2Gb memory, solid state hard drive, 16gb
Asus Zenbook nip	ram
Lenovo Y520	15IKBM i7-7700hq, 16GB, gtx1060
Acer Predator PH317	i7, GTX1060, 16G RAM
MSI – GS63VR	7RF stealth pro RAM 32G
Alien	
ALW15M-R2726R	_
ASUS ROG STRIX	-

1.2. Scanner Set Up

Unpack and set up your scanner and software before getting started with scanning.

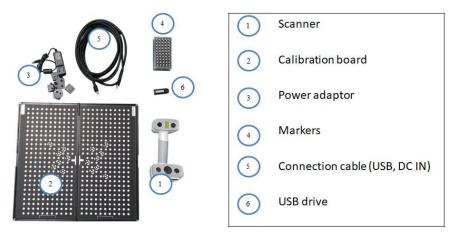
1.2.1. Unpack the Box





Note:

The case is optional. Contact your supplier if you want to buy one. Packing list

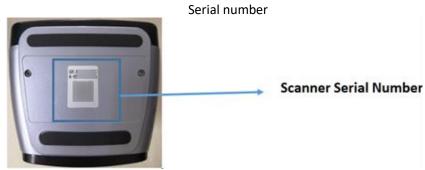


Package

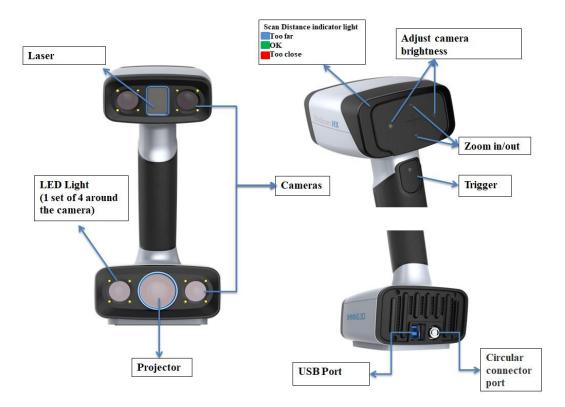
The items listed in the packing list refer to the components and material that should be included in the package. The components may be different as listed when you purchase other accessories or change any item with your supplier. Please check carefully when opening the package.

Note:

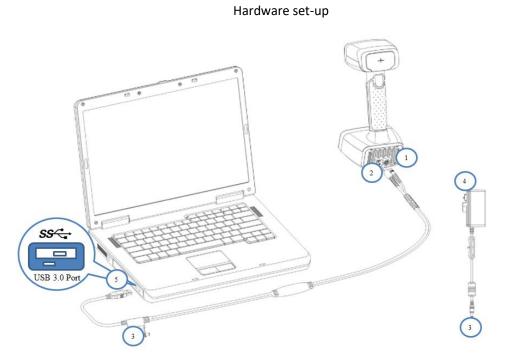
Each scanner has its own serial number, label is placed at the bottom of the scanner. It will be required for maintenance. Do not remove it.



1.2.2. Scanner Body



1.2.3. Connection



Step 1: Take out the connection cable. Step 2: Insert the pin plug into the scanner's circular connector port. Step 3: Plug the other one to scanner's USB port.

- Step 4: Plug the power adaptor into the connection cable DC in port.
- Step 5: Plug the power cable another end into a power outlet.
- Step 6: Connect the other end of the connection cable to a USB 3.0 port on your computer.

2. Software Set Up

2.1. Download the Software

Step 1: Go to https://www.einscan.com/support/download/.

Step 2: Select your scanner model.

Step 3: Download the software to your operating computer.

Note:

You are required to register before downloading.

2.2. Install the Software

Note:

- Administrator rights are required for the installation of the software.
- Do not install EXScan under directory of Program Files and Program Files (x86) in local disk. Permission issue might result in EXScan error.
- You are not suggested to put task bar on the interface edge when using EXScan.

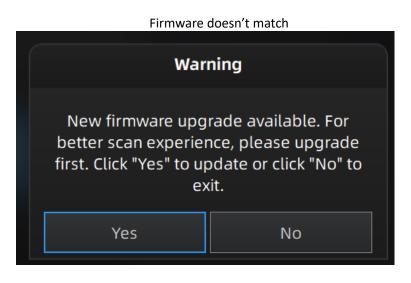
Step 1: Double click installation package, accept the modification on your computer. Step 2: Follow the instructions to complete the software installation.

Step 3: After the software is installed, a shortcut ⁽¹⁾ will be created on your desktop. Double-click to open the software.

2.3. Firmware Update

When the scanner firmware is incompatible, a message will appear when software is open. Click Upgrade and follow the instruction to update the device firmware.

- Firmware updating will take around 6 mins.
- Power off the device after upgrading successfully.
- Reconnect the device, and open the software again, the device is running under the latest firmware.



Firmware upgrading

Firmware is upgrading
Firmware is upgrading, please do not cut off the electricity.
36%

Note:

- Do not disconnect the scanner, or unplug the power during the upgrade.
- Recovery will start from a failed upgrade. You can restart the firmware update after successful recovery.
- If recovery fails, turn off the power of the scanner and reconnect the scanner to restart the software for upgrading.

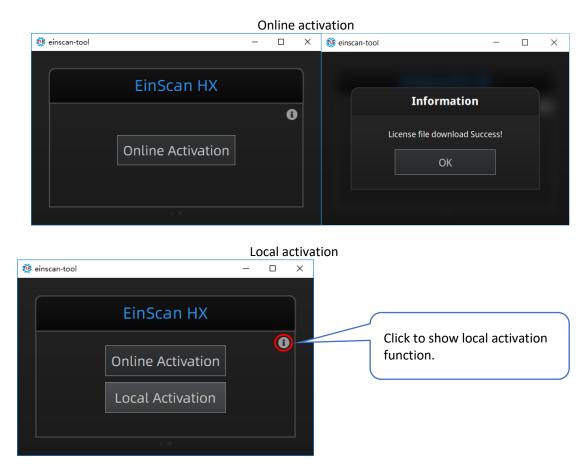
2.4. Device Activation

Device activation is required in your initial use. There are 2 ways:

- **Online activation** is recommended if your computer is connected to the internet.
- If there is an issue with network connection, choose Local activation to save the .ple license file on your computer, under the activation menu. (.ple file can be found in the USB drive.)

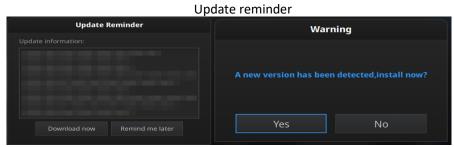
Note:

If the activation fails, send a request for activation file to einscan_support@shining3d.com with your serial number.



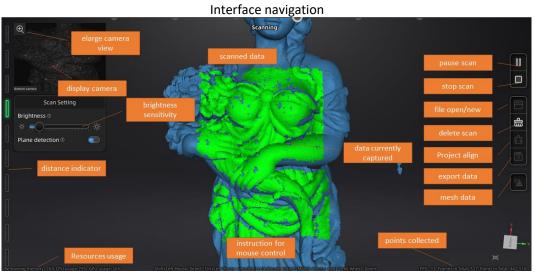
2.5. Software Update

When a new version is available, a pop-up will show when you start the software to remind you update your software to the latest version. You are recommended to click **Yes** for new feature experience.



2.6. Interface and Parameters

2.6.1. Navigate



Left mouse: Rotate. Middle mouse: Move the data. Scroll up and down: Zoom in or out. Keyboard: Spacebar to scan again or restart the scan & validate. Delete key to delete selected data. Esc key to exit current pop-up.

Navigate between different menu by click on the circle.

Navigation bar

Device	Calibration	Scan Mode	Scan
EinScan HX	Aug.03 - 18:36	Rapid Scan	In Progress
	•		

2.6.2. Device Reconnection

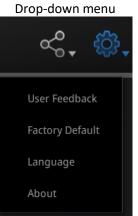
When the device is offline, meaning the scanner is not connected to PC, please check the connection and click on the refresh connection button to reconnect. Device offline or connection loose





2.6.3. Settings

Click from the upper right to open the drop-down menu.



Feedback

If you have any questions or suggestions, please share with us by clicking "Feedback". Leave your email in "My E-mail."

Feedback window				
	User Fe	edback		
Do you have	e any questions	or suggestions for	us ?	
* My email:				
				+
🗹 User expe		program <u>Learn more</u>		
Technical Supp				
	Submit	Cancel		

User Experience Enhancement Program

To help us improve the quality and user experience of EinScan, we hope to be allowed to collect usage experience information. This information will not contain your personal information or scanned data, and will not be accessible to any third party. This checkbox is selected by default, and we strongly recommend you keep it checked. As a reward, the User Experience Enhancement Program will continuously keep you informed with the newest software update information, to assure you get free software updates and enjoy the latest improvements based on your collective feedback. If you close the User Experience Enhancement Program, you might not be informed with software updates automatically.

Factory Default

All settings modifications will go back to the original settings.

Language

Select the language for the interface, click apply to change, restarting the software is not needed.

About

For version information and support, email: einscan_support@shining3d.com.

2.6.4. EinScan Community

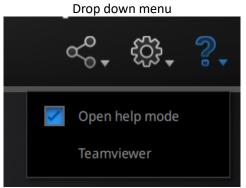


- Official Website (http://www.einscan.com/) refers to SHINING3D's official website for Einscan product and information.
- **Facebook** (EinScan) refers to facebook "EinScan Expert" for EinScan users to discuss and share the ideas, achievements and experience.
- Support Platform refers to the platform for EinScan users to validate the warranty and submit support ticket when necessary. Service live software updates, manual, video download can be accessed in support platform. Register your EinScan at support.shining3d.com.

2.6.5. Help Mode

Open Help Mode

Click the question mark in the upper right bar, and open the help mode from the drop-down menu.



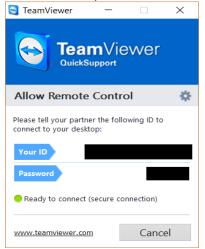
Display the help tool related to the current interface.



TeamViewer

It opens S3D_teamviewer.exe, for online customer support access or display to other screens or portable screens. Share your ID and password to allow our technicians to remote control of your computer during online technical support.

Share the Your ID and password to allow access



2.6.6. Alerts

A pop-up alert will notify the user of a hardware or configuration issue. Check and restart the software. If the error persists, contact support by emailing einscan_support@shining3d.com.

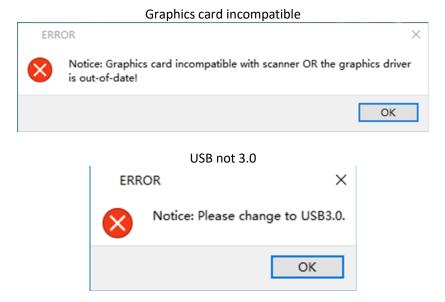
Fail to Activate

For activation failure, make sure the scanner is well connected. Redo the activation. Device fails to activate

WARNING: The license file doesn't match the scanner. Activate

Incorrect Configuration

Try another USB port and update your graphics card drivers and restart the software.



If the computer has multiple graphic cards, access to the NVIDIA Control Panel (right click on the desktop). In Manage 3D Settings > Program Settings, Add EXScan software. Then change the preferred graphic processor for this program. Select NVIDIA processor. Click Apply to save the settings.

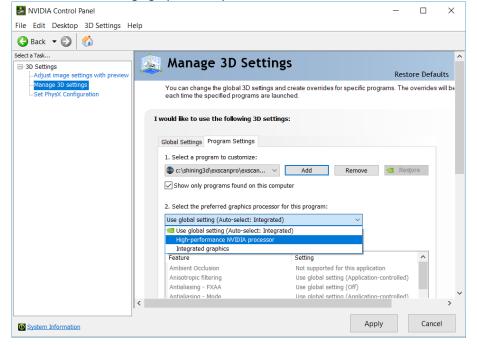
 Multiple graphic cards detected

 EXScan

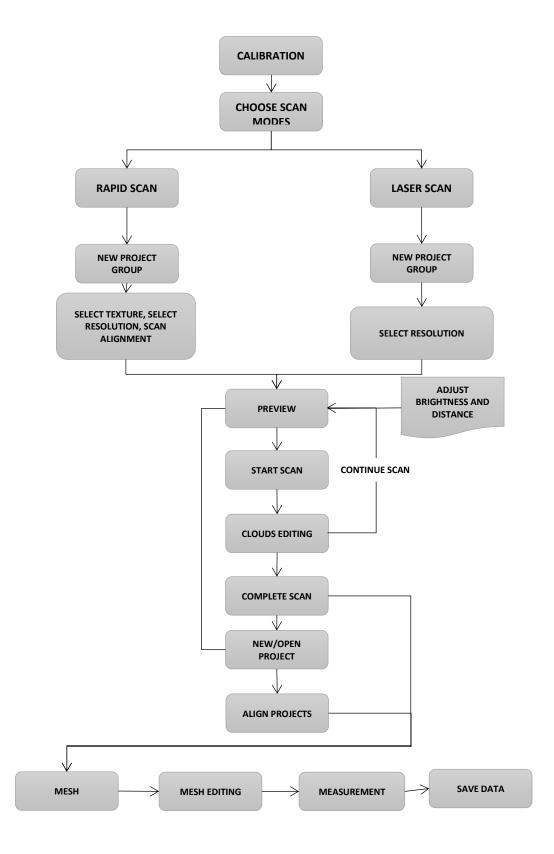
 i

 Notice:Multiple graphics cards are detected, please disable other graphics cards and keep high performance NVIDIA independent graphics cards.Otherwise, the performance of scanning software may be affected!

Change graphic card preferences for EinScan HX



3. Software Scan Workflow



4. Calibration

4.1. Precautions and Use

Calibration is the process to ensure the device will scan with the optimal accuracy and scan quality. Each EinScan 3d scanner was factory-tested and achieved, at least, the listed accuracy from the technical specification according to VDI/VDE 2634 standards.

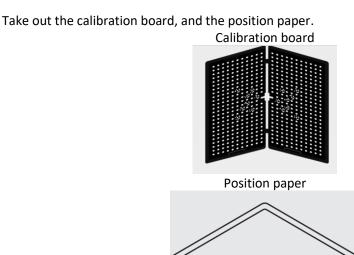
Besides factory tested guarantee of accuracy, to assure high scanning accuracy, each EinScan is also coming with a calibration board for customer calibration. This customer calibration is not required daily often. Only when the first time after scanner and software are installed. Or, when you are in the following situations, you should calibrate the device:

- Device change.
- After device enduring bumpy transportation.
- After device accuracy decreases.
- When data misaligned very often.

Note:

- Customer calibration is recommended to do twice a week for daily use.
- Make sure to protect the calibration board and keep it clean, no scratches or stains on the black surface with white circles.
- The Calibration board is matched to the Device with same Serial Number. Doing the calibration with an incorrect calibration board will fail to generate good scan data or optimum accuracy.
- Clean with clear water only, do not use alcohol or chemical liquid to clean the calibration board.

4.2. Preparation for Calibration



4.3. How to Calibrate

Calibration includes:

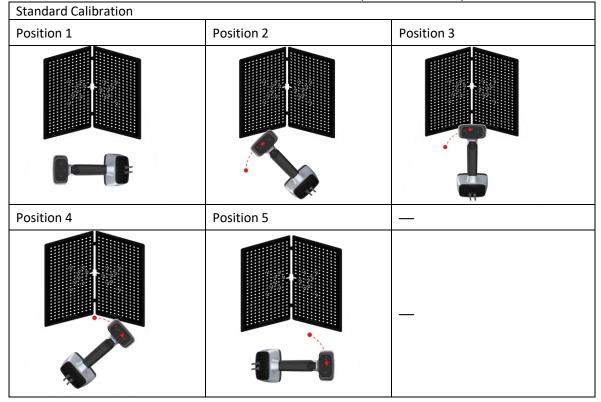
- STANDARD CALIBRATION
- LASER CALIBRATION
- WHITE BALANCE
- QUICK CALIBRATION

In the initial use, you will be guided to **STANDARD CALIBRATION** directly.

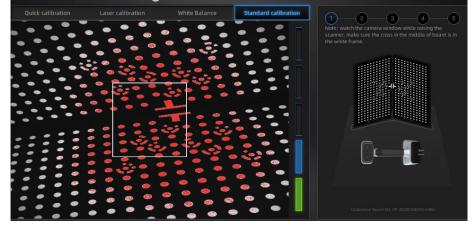
Step 1: Put the calibration board vertically onto the paper position.

Step 2: Follow the instructions from the software to finish 5 positions.

Step 3: While holding the scanner, make sure it is upright to the center of the board. Bring the scanner closer or farther to the board till all the required distance captured.

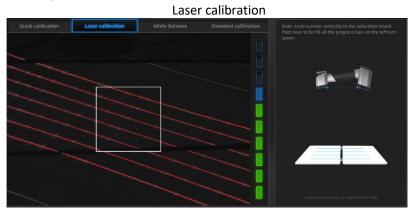


Standard calibration (Point the scanner at the center of the board)

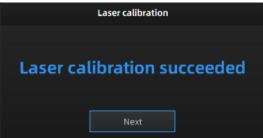


Calibration succeeded		
Camera Calibration		
Calibration succeeded		
Calibration deviation:0.044263 Pixel		
Next		

A pop-up of **Calibration Succeeded** will appear. Click Next on the pop-up, software will take you to the next step: laser calibration. Put the back side of the board on a stable and level table, and point the scanner upright to the board. Move the scanner up and down till all the required distance captured in green.



Laser calibration succeeded

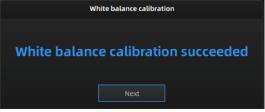


A pop-up of **Calibration Succeeded** will appear. Click Next on the pop-up, software will take you to the next step: WHITE BALANCE. Put the back side of the board on a stable and level table, and point the scanner upright to the board. Move the scanner up and down till a photo taken at a right distance.

A pop-up of white balance calibration succeeded will appear. Click Next on the pop-up, you will enter to scan mode.

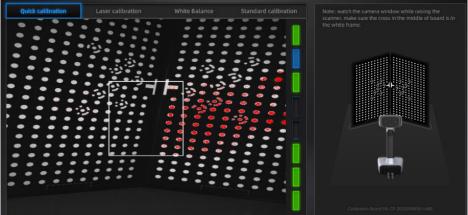


White balance calibration succeeded

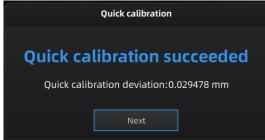


QUICK CALIBRATION is recommended when recalibration is required. Only one position is required. A pop-up of Calibration succeeded will appear. And then go to next step to finish **LASER CALIBRATION** and **WHITE BALANCE**.





Quick calibration succeeded



Note:

- Customer calibration is recommended to do twice a week for daily use.
- Move the scanner at a steady and slow speed.
- Make sure to protect the calibration board and keep it clean, no scratches or stains on the black surface with white circles.

- The Calibration board is matched to the Device with same Serial Number. Doing the calibration with an incorrect calibration board will fail to generate good scan data or optimum accuracy.
- Clean with clear water only, do not use alcohol or chemical liquid to clean the calibration board.

If the calibration failed, check:

- If there are any reflective object or strong light nearby, recalibrate to avoid the reflective and strong light.
- If the positions were followed as suggested, recalibrate according to the suggested steps.
- If the board is clear and clean without scratches or stains.

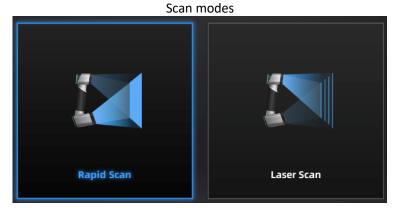
5. Before Scanning

5.1. Scanner Buttons



5.2. Scan Modes

Now you can start to scan. Use EinScan HX, you can use Rapid Scan by structure light scanning for a fast scan, or use Laser scan by laser triangulation to scan some difficult.



	Laser Scan	Rapid Scan
What to scan?	300mm - 4m objects	
Light source	Laser	LED

Accuracy	0.04mm	0.05mm
Resolution	0.05mm-3mm	0.25-3mm
Alignment	Markers	Markers/features/ hybrid/texture
Scanning speed	50FPS	15fps (non-texture); 10fps (texture)
Texture Scan	No	Yes

5.3. Preparation

5.3.1. Rapid Scan

We do not recommend scanning:

- Moving or vibrating objects, which cause the shape of object changed during scanning process.
- Soft material object.
- Lattice structures with many small deep holes.

The objects, which has good geometry or texture features will get scanned very easily and fast with good quality.

If you have to scan the items like below, do preparations before scanning and notes during scanning.

	Preparation	Notes while scanning
Black, transparent, shiny, reflective surface objects	Use washable or vanishing scanning spray.	Scan as normal.
Objects with loss features	Place markers on the objects.	Select marker alignment.
Objects with less feature or repetitive features	Mark/draw on the surface to add features.	Select texture alignment.
Thin wall objects	Place markers on and around the objects.	Choose global marker alignment.

5.3.2. Laser Scan

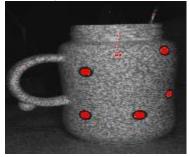
When you stick markers on the surface of the object, you need to follow the following rules:

- Make sure sticking at least 3 markers in each frame (one scanning field of view).
- Control the number of markers seen on the camera view.
- Stick markers in a random, non-linear pattern.
- Markers should be stuck on the flat surface area and keep the marker surface flat.
- Use the markers provided with the device only. Other markers can result in bad accuracy or not to be seen.

• Spraying powder is not necessary for scanning black, transparent or shiny surface. **Note**:

Laser line will not be projected when markers are not recognized.

Object with markers



Warning:

EinScan HX uses a class I laser when using laser scan mode, which is eye and skin safe under all conditions of normal use, but long time staring at the laser beam directly is not suggested. Avoid direct eye contact with the laser beam. Keep the laser beam away from children.

6. Project

You can start with a new project or open an existing project to continue the scanning.

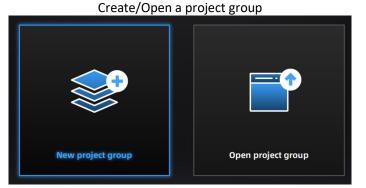
6.1. New Project Group

To create a new project, select the File, and name the project. The default project is saved to the desktop. You can change the saving path, and then the newly created Work will be saved to the new location you chose.

6.2. Open Project Group

To open an existing project, select the file, and choose the project has been saved. **Note**:

The projects should be scanned under the same scan mode.



6.3. Pre-setting

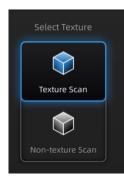
6.3.1. Select Texture

TEXTURE SCAN: The scan will be with color, and it also allows texture alignment. It is only available in Rapid Scan mode.

NON-TEXTURE SCAN: The scan will be without color.

Note:

Texture scan requires the objects to have colorful texture surface, and it takes longer time for data processing when meshing.



6.3.2. Alignments

RAPID SCAN allows 4 alignments by markers/features/ hybrid/texture. While **LASER SCAN** is default setting of marker alignment, no other options of alignments, so markers on objects need to be prepared in advanced.

FEATURE ALIGNMENT uses object geometric features for auto aligning during scanning. Rich features on the object are required for this mode.

MARKER ALIGNMENT uses markers to align the scans. It will help tracking for some object with non-feature regions like flat, spherical surface or objects with repetitive features. Preparation of marker on the object is required before scanning.

HYBRID ALIGNMENT uses features and markers to align the scans. By this alignment, we don't need to place the markers all over the part, but only on the region where has less geometry.

TEXTURE ALIGNMENT uses objects surface texture to align the scans. Texture Scan is required to select if you want to use texture align.



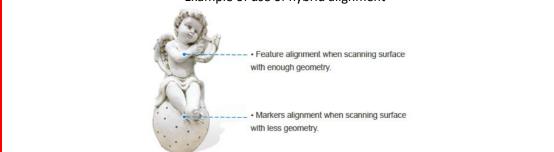
Global markers alignment: Select marker alignment or hybrid alignment, and then import global marker to implement global markers scan.

Note:

Marker alignment:

- 1. Place on flat regions.
- 2. Avoid the geometric regions.
- 3. Stick the markers in a random, non-linear pattern.
- 4. Some cases like small objects, we suggest distributing the markers on a black surface around the object.
- 5. Use the markers coming with your device. Other markers can result bad accuracy or not be able to be detected for scanning.
- 6. While scanning, make sure at least 4 markers in each frame can be taken.

Example of use of hybrid alignment





High color contrast

Texture align result:

Rich-colored



- Solid color
- Texture align result:
- $\overleftarrow{}$

When selecting texture alignment, hold the scanner to move evenly steady.

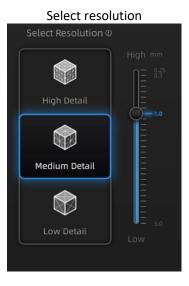


6.3.3. Resolution

Select a resolution for the project. The higher the resolution, the better the details, but this may lead to larger files and processing times.

Choose High, Medium or Low or drag the cursor to choose another point-distance setting from the bar.

Resolution	Laser Scan	Rapid Scan
Scope	0.05~3.0mm	0.25~3.0mm
High Detail	0.2mm	0.7mm
Medium Detail	0.5mm	1.0mm
Low Detail	1.0mm	1.5mm



6.3.4. Global Marker File

Note:

For global marker operations under laser scan mode, you can still follow the following steps (Step 1—Step 6).

When selecting marker alignment in Rapid Scan, you will find an option of "open global markers file". It allows you to import .asc, .p3 marker files by using a combination of marker frame or photogrammetry measurements. By this method, we can scan large scale objects for a better accuracy. It will also help scan thin-wall objects to merge the front and the back side more accurately.

Step 1: Follow your photogrammetry system operation; you can also set up a marker frame on the object, scan it by marker alignment.

Step 2: Save the point model in .asc or .p3 file.

Step 3: Open new project group and marker alignment.

Step 4: Import the saved .asc or .p3 file.

Step 5: Scan the object.

Step 6: The scans will all aligned according to the global marker file.

Open global markers file

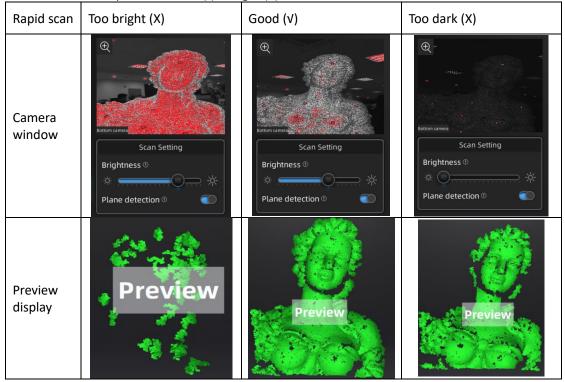
	Open global markers file:		Browse	
Not	Under rapid scan mode, hybrid alignment.	global marker file is only available when se	electing marker	or
•	Under laser scan mode, gi	obal marker file is always available.		

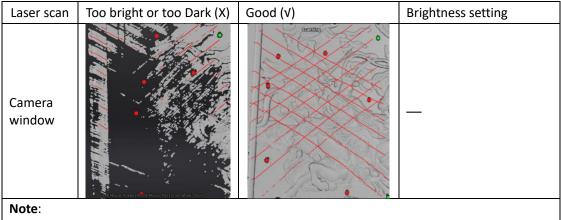
6.4. Scan Setting

Entering to SCAN interface, there are some settings to be noticed before scanning:

6.4.1. Brightness Adjustment

You can adjust the brightness by clicking " or " on the scanner, or drag the cursor under the camera preview to left (-) or right (+).

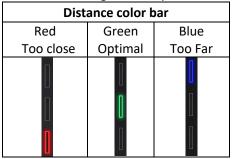




Brightness setting will be selected after object selected. When the laser traces and markers are not detected, the data will not be captured much.

6.4.2. Optimal Distance Range

When the scanner is too close or too far from the object, it will lose tracking. An optimal distance is important. You can observe the distance color on the scanner or color bar on the software. If tracking is lost, reposition the scanner to the scanned area at a proper distance.



o the scalled alea at a proper distance.		
Distance color on scanner		
Red Green Blue		Blue
Too close	Optimal	Too Far

Scan mode	Resolution	Minimum distance	Optimal distance	Maximum distance
	0.25~0.5mm	200mm	300mm	400mm
Rapid scan	0.5~0.7mm	200mm	325mm	450mm
	0.7~3.0mm	200mm	470mm	600mm
Laser scan	0.05~3.0mm	370mm	470mm	570mm

6.4.3. Other Settings in Rapid Scan

TEXTURE FLASHING: LED on/off. Suggest to always on for texture uniformity. When OFF must be chosen, make sure your ambient light is well distributed Only available when selecting scanning with texture.

PLANE DETECTION: Enable to detect the surface flatness. Suggest ON when selecting feature or hybrid alignment. When there is less geometry, software will remind "not enough features to align". If you do not choose the plane detection, you could still scan flat surface, but the misalignment will happen.

Plane detection on when not enough features to align

Not enough features to align	
Scan other setting	
Project group Scan Setting	
Brightness ①	
* •••••• *	
Plane detection 🛛 🛛 🌑	
Texture Flashing 🛛 🛛 🌑	

Marker recognition enhancement: The function is available only when selecting marker and hybrid alignment. More sensitive marker recognition when scanning dark targets but with low scan accuracy.

6.4.4. Other Settings in Laser Scan

Scan mode: There are options of scan point cloud and scan markers.

- Add global markers: When scanning markers in the specific area, you might also scan markers around the specific area (simply to say, surrounding global markers). To add surrounding global markers into the original global markers, import global markers, switch to point cloud scanning and select Add global markers.
- Scan global markers: Only scan markers. Acquire marker data fast. There is no laser line in the scanning process. Markers can be scanned to supplement in the global marker file generated before.
- Scan point cloud: Acquire the data as point cloud. It could be switched to scan point cloud mode after scanning markers. It is also feasible to import the generated global marker file and then scan the point cloud.

Note:

- After scan point cloud data, if it is switched to scan markers mode or imported GMF, the current point cloud will be deleted.
- Only after new project, generating point cloud or optimizing markers, you can switch between scan point cloud and scan markers.

Object: Choose the object surface material accordingly: Reflective, Normal, Black.

Data setting: Scanning some black glossy object, when brightness is already set to its limits,

but still very less data is captured. Turn the data setting cursor from left 🤷 to right 🥯 . It will help scanning, but with noise.

Global markers scan. After creating a new project, select Scan Point Cloud or Scan Markers. See "5.3.2 Laser Scan."

Scan other settings

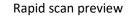
0
Project Group Scan Setting
Scan Mode ①
🗹 Open global markers file
Scan Point Cloud
Add global markers
Scan Markers
Object ^①
◯ Normal ◯ Reflective ◯ Black
Brightness ()
☆ ↔
Data setting ①

7. Scan

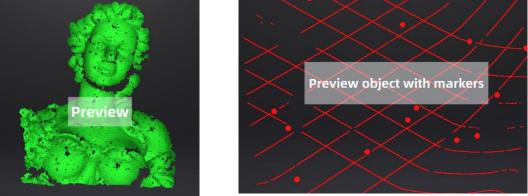
7.1. Preview

Click the trigger on the scanner or in the software, you will enter the Preview mode. In this mode, it will start to show data for preview, but not record this data. In this mode, you can:

- Adjust the brightness sensitivity, refer to BRIGHTNESS ADJUSTMENT.
- Check the working distance, refer to OPTIMAL DISTANCE.
- Inspect markers recognition, refer to MARKER ALIGNMENT.



Laser scan preview



7.2. Start/Pause/Continue/Stop Scanning

Click the trigger again, scan will start, and data is recorded. During scanning make sure to keep the scanner perpendicular to the surface, keep a proper distance from the object, and adjust the brightness depending on the ambient light and texture of the object.

Click Start in software or press the Play button to exit the preview mode and start the scan.

Note:

- Preview mode will start every time a new project is built, or an existing project is imported, or continue scanning after each pause.
- Click Start in software or press the Play button to exit the preview mode and start the scan.

7.3. Resume Scanning After Tracking Lost

If the scanner can't capture common features (when feature alignment is selected), miss enough markers (when marker alignment is selected or under laser scan), or with unclear texture (when texture alignment is selected), it will stop data capturing. The software will remind tracking lost on the interface with sound. You can point the scanner at any scanned regions, and the scanning will be resumed. Besides of the above alignment requirements, moving too fast, scanning distance, and the object surface too dark or shiny will also cause the tracking lost. Refer to PREPARATION, DISTANCE, BRIGHTNESS ADJUSTMENT for more tips.

The green color on the data shows the current captured region





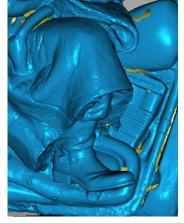
7.4. Generate Point Clouds

Click click

Then you can select, delete data to use the edit tools.



After generating point cloud

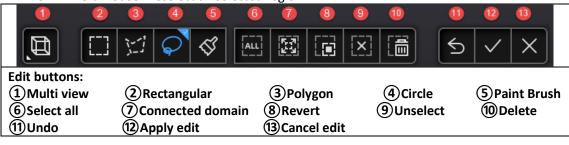


7.5. Clouds Editing

CLOUDS SELECT/DELETE

SHIFT + Left mouse: Select unwanted data, the selected section will be displayed in red, as shown below.

CTRL+ Left mouse: Deselect an selected region.



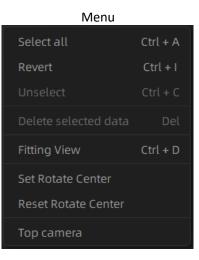
Ś	Paint Brush Mouse scrolling wheel to adjust the paint brush size.	
	Connected domain Click the button after select the data, all connected region to the selected data will be picked.	
	Delete selected data Click the button or "DELETE" on the keyboard to delete selected data.	
5	Undo You can only undo the most recently deleted data.	
\checkmark	Apply edit Click the button or space bar to apply the edition, and exit edit mode.	
\times	Cancel edit Undo all editors, and exit edit mode.	

Note:

Don't support markers editing.

7.6. Right-click Context Menu

Right click, and there will be the context menu as below.



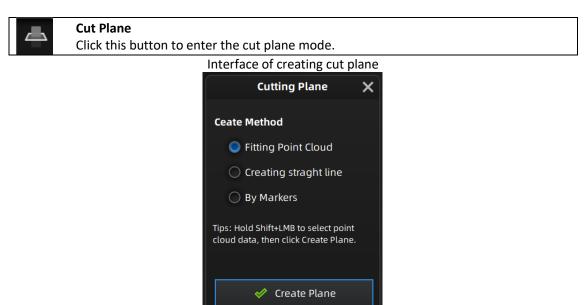
Function	Explanation
Select all, Reverse, Deselect all,	The same function as Edit. Available with shortcut key.
Delete	The same function as Eult. Available with shortcut key.
Fitting view	Make the data show in the middle and in a proper size.
Rotation center	Set the rotation center in the data by left click. Quit by ESC key.
Reset rotation center	After reset, the rotation center is in the middle of the data.
Top camera, Texture camera	Click to show the corresponding camera view in the top left.

7.7. Cutting Plane

Cutting plane is very useful when a base need to be removed during scanning. You can orient the plane around X,Y, Z axes. The plane can be rotated, zoom, move.

After setting cut plane, there will be no more data scanned below the cut plane during the scanning process, preventing irrelevant data getting scanned.

Create Cut Plane



Fitting Point cloud: Press Shift + left-click to select data, then click the button "Generate plane". The cut plane will be created by point cloud fitting. The direction of the plane will be calculated by the software according to the direction of point cloud.

Creating straight line: Press Shift + left-click to draw a line, and generate the cut plane according to the line.

By Marker: Press Shift + left-click to select markers. 3 markers or more are required to generate the cut plane.

• Cut Plane setting

Rotation axis: Cut plane can be rotated around the axis by operating the active bar, editing the text box or placing the cursor on the edge of the cut plane and dragging.

Translation increment: Translate the cut plane by operating the active bar, editing the text box or placing the cursor in the center of the cut plane and dragging. After translation, the increment value will be reset to 0.

Delete: click this option, data in the reverse direction will be shown in red. Apply this, and the red data will be deleted.

Reverse: Reverse the normal direction of the cut plane. Delete plane: Delete the created cut plane.

Other operation

Mouse operation: Double click the cut pane to enter the cut plane setting after quitting the cut plane interface.

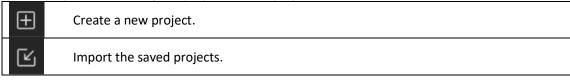
Hide/Show cut plane: After creating the cut plane, hide or show the cut plane by right click. **Notes**:

- Cutting Plane Operations: Create a new cutting plane, remove cutting plane, reverse normal, delete data (Markers can't be deleted).
- Cutting plane operation is only workable under the current project.
- Scan with Cutting plane: Only one side from the cutting plane can be scanned. Cutting plane is very useful when a base need to be removed during scanning.

8. Project Group

8.1. Create/Import Projects

When the scan data is saved, you can create new projects with more scans, or import the saved projects and manage all projects on the project tree.



Note:

Only projects from the same scan mode and with the same resolution can be imported. Right click menu



8.2. Remove/Delete Projects

Ð	Remove the project.
Š	Delete the selected project(s).
<u></u>	act one or multiple projects by click remove to remove the project(s) from the project

Select one or multiple projects by click remove to remove the project(s) from the project tree, but not from the local folder. It can be imported when it is needed.

Click Delete or right click and delete to delete the selected project(s) from the project tree and the local folder.

8.3. Align Projects

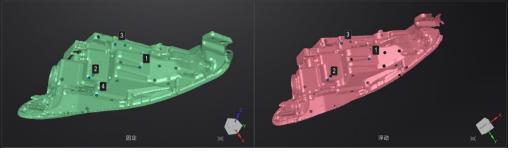
Click **Click** to open the Manual Alignment interface. There are two ways to align:

- Feature Alignment Select feature align, click "apply" button, software will align the scans based on the features automatically.
- Manually Alignment

Press SHIFT and left click mouse to choose not less than three common but nonlinear points in the fixed and floating views, click "apply" to merge.

Press Ctrl + Z or ESC button to cancel the point selection by order.

Align



Working Principal: Calculate the best match of the selected points, merge the scans according to the best fit of the points in the fixed and floating views.

Marker Alignment

You could choose marker alignment if the projectors are with markers. There shall be at least 3 common markers in two projects, otherwise the alignment will fail. Software will align the projects according to the positions of those markers automatically.

Click "Apply" to align.

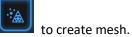
Click "**Next**", the aligned projects will merge to a group, you could continue further alignment. Click "**Cancel**" to recall the alignment.

Click "Exit" to exit project alignment interface.

9. Meshing

9.1. Create Mesh (Watertight/Unwater tight)

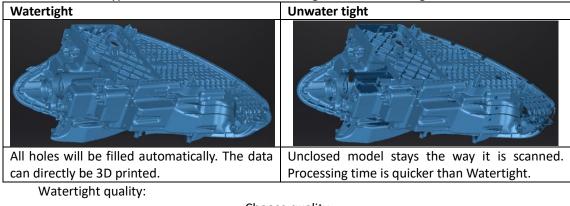
When scanning and editing are completed, click



🔵 Low

9.1.1. Mesh

There are 2 types of mesh are available: Watertight and Unwater tight.



Choose quality Mesh Unwatertight Quality 🔵 High 🥥 Med

TEXTURE WATERTIGHT

The texture capture is separate from the 3d data capture. If the texture has been captured, it will still be displayed on areas where holes are filled in the mesh processing. If the texture is missing, the corresponding mesh data will be in black.

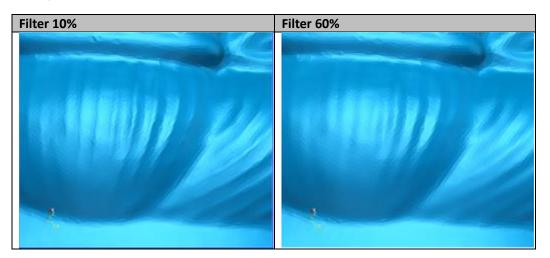


This region was missing in the scanning, and the texture can't match the original texture.

9.1.2. Mesh Optimization

Through the toolbar on the left, you can simplify, optimize, remove small floating parts, remove spike and marker hole filling.

Use recommended parameters: To get EXScan HX help you optimize a specific model, enable the function. To customize parameters, disable the function.

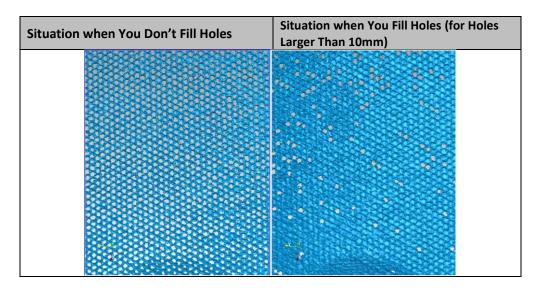


Filter: Optimize data.

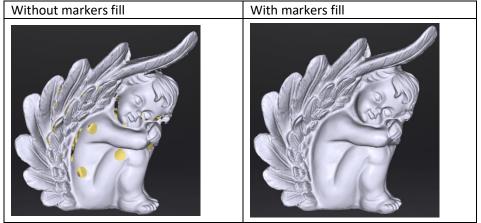
Remove small floating parts: See "9.2 Mesh Editing"—"9.10 Texture Remapping."

Max triangles: Set max. plate number to get mesh model's triangle plate number is within configured plate number.

Fill small hole: For objects with tiny holes (larger than 10 mm), use the function to fill tiny hole to make the scanned image look better. For objects with holes (smaller than 10 mm), you are not recommended to use the function or you can set the function parameter value to a smaller one.



Remove spikes: Remove spike-like data on the image edge.



Marker hole filling:

9.2. Mesh Editing

The mesh can be edited: Select/delete, Hole filling, Sharpen, Smooth, Simplification, Multiview.

MESH SELECT/DELETE

Press **Shift + Left mouse** to select data and enter the selection menu. **CTRL+ Left mouse**: Deselect a selected region.

CLOUDS SELECT/DELETE

SHIFT + Left mouse: Select unwanted data, the selected section will be displayed in red, as shown below.

CTRL+ Left mouse: Deselect a selected region.

	4 5 6 7	8 9 10 11 12	13 14 15
			5 < X
Edit buttons: ①Multi view ⑤Polygon	②Select Visibl ⑥Circle	e ③Select Thr ⑦Paint Brush	ough ④Rectangular ⑧Select all

(9)Conne	ected domain	①Revert	1) Unselect	12 Delete
(13) Undo		4 Apply edit	(15) Cancel edit	
\diamond	Select Visible	1		
\diamond	to select data	on the front view on	ly	
\diamond	Select Throug	gh		
\diamond	to select data	all though		
R	Paint Brush			
\sim	Mouse scrolli	ng wheel to adjust th	e paint brush size.	
19773	Connected de	omain		
	Click the butt	on after select the da	ata, all connected region to t	he selected data will be
	picked.			
	Delete select			
	Click the butt	on or "DELETE" on th	e keyboard to delete selecte	d data.
5	Undo			
	You can only	undo the most recen	tly deleted data.	
	Apply edit			
Ý	Click the butt	on or space bar to ap	ply the edition, and exit edit	mode.
\sim	Cancel edit			
	Undo all edite	ors, and exit edit mod	le.	

9.3. Texture Adjustment

When the mesh model has been generated, use the cursors to change the Brightness and/or contrast of the texture from -100 to +100. The default value is 0 for both.

- Brightness (-100-100): indicates the brightness of the picture. The larger the value is, the higher the brightness is.
- Contrast (-100-100): indicates the degree of contrast between colors. The larger the value is, the more obvious the color difference is.



: Click Reset to return to 0.

Modify texture
Texture
Brightness
Contrast
Confirm Cancel

This modification is not saved in the project file. Export the data to save the texture editing.

9.4. Simplification

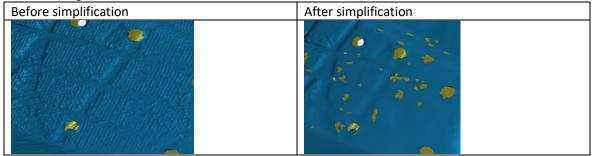
After simplification, the polygon numbers, file size and level of detail of data will be reduced accordingly. Set the ratio from 1 to 100, the default is 0.

The comparison of detail between before simplification and after simplification (at 70% simplify proportion).

Simplification menu							
Simplification							
o		□ 0 ♦ C					
	Original	Simplified					
STL (MB):	30.43	30.43					
OBJ (MB):	41.21	41.21					
Polygons:	625946	625946					
Apply	Confirm	Cancel					

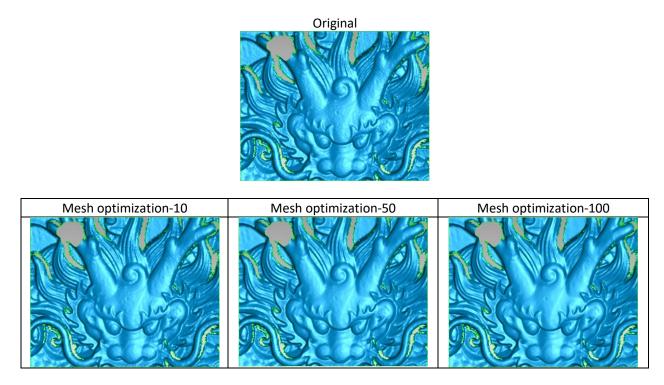
Click "**Apply**" button to simplify data, preview the result of current setting. Click "**Confirm**" button to apply the "Simplification" setting. Click "**Cancel**" button to quit, and go back to the original data.

Multiple operations on "Simplification", the result will not be added. It will always operate on the original data.



9.5. Mesh Optimization

Mesh optimization can optimize the quality of the data. There are 3 ratio options of mesh optimization. Processing time will be different. Below shows the result of 3 different ratios.

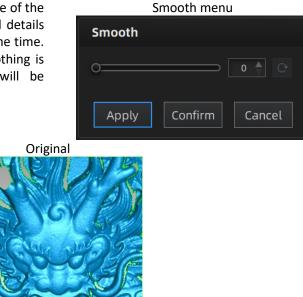


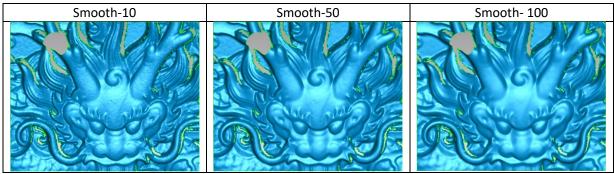
Click "**Apply**" button to optimize data, preview the result of current setting. Click "**Confirm**" button to apply the "Mesh Optimization" setting. Click "**Cancel**" button to quit, and go back to the original data.

Multiple operations on "Mesh Optimization", the result will not be added. It will always operate on the original data.

9.6. Smooth

Smooth the possible noise on the surface of the scan data. It might remove some small details or smooth some sharp edges at the same time. The example of before and after smoothing is shown below. Run 2 times, data will be smoothed twice.





Click "**Apply**" button to smooth data, preview the result of current setting. Click "**Confirm**" button to apply the "Smooth" setting.

Click **"Cancel**" button to quit, and go back to the original data.

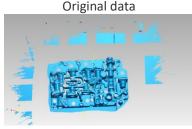
Multiple operations on "Smooth", the result will not be added. It will always operate on the original data.

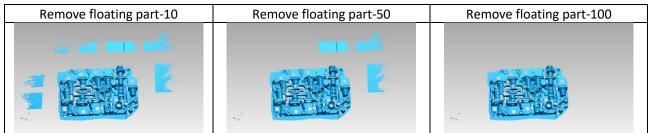
9.7. Remove Small Floating Parts

Remove small floating parts in the scan data.

0 means no operation, 100 is the maximum. The maximum value is the square of the diagonal length of the floating part/10, MAX= $(L/10)^2$.

Diagram of removing floating parts shows as below:





Click "**Apply**" button to remove floating part, preview the result of current settings. Click "**Confirm**" button to apply the "remove floating part" setting.

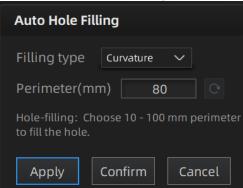
Click "Cancel" button to quit, and go back to the original data.

Multiple operations on "Remove floating part", the result will not be added. It will always operate on the original data.

9.8. Auto Hole Filling

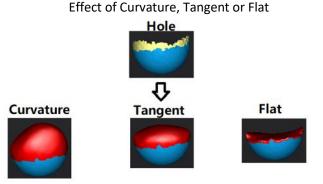
Input the perimeter of the biggest hole to be filled. Less than 100mm is recommended. This function will fill every hole with a smaller perimeter than the number input.

Auto hole filling



Choose Curvature, Tangent or Flat before filling hole.

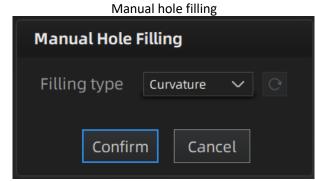
- **FLAT** calculates the solution for the hole filling considering the point position on the boundary.
- **TANGENT** calculates the solution considering the point position and the normal of the last row of triangles forming the boundary.
- CURVATURE calculates the solution considering the point position and the normal of the 2 last rows of triangles forming the boundary.



Click "**Apply**" button to auto fill hole, preview the result of current setting. Click "**Confirm**" button to apply the "Auto hole filling" setting. Click "**Cancel**" button to quit, and go back to the original data.

9.9. Manual Hole Filling

The hole edges are displayed green, and get red after picking. The number of the holes and the number of holes filled will be displayed on the interface. Choose Curvature, Tangent or Flat before picking a hole.



Click the edge of the hole to fill it.

🔍, according to the order of filling holes, from the last hole to cancel hole filling. Ctrl Click + Z can also cancel hole filling.

Click "Confirm" button to apply current setting and exit the manual hole filling. Click "Cancel" button to quit, and go back to the original data.

9.10. Texture Remapping



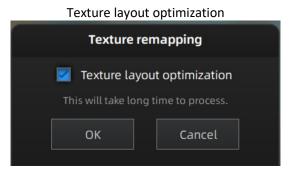
Texture Remapping to display the Texture menu.

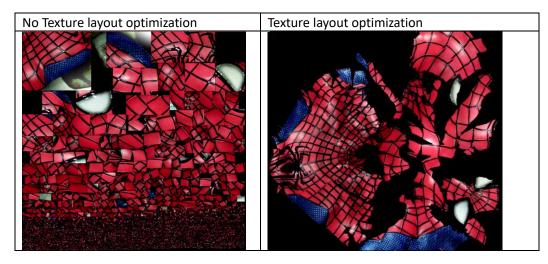
Mesh edition of simplification, hole filling on texture scanned data will affect the texture render. By doing the texture remapping, the texture information will be reapplied on the mesh.

Texture remapping is accessible before saving the data.

Choose "Texture Layout Optimization" (TLO) to create an optimized arrangement for the texture file. It will make the texture manual editing much more convenient if you are going to process the texture in a 3rd party software.

This option has no effect on the texture itself.





Note:

- TLO requires a longer time to compute. •
- TLO is used only with OBJ output.
- TLO result is more convenient for texture manual editing.

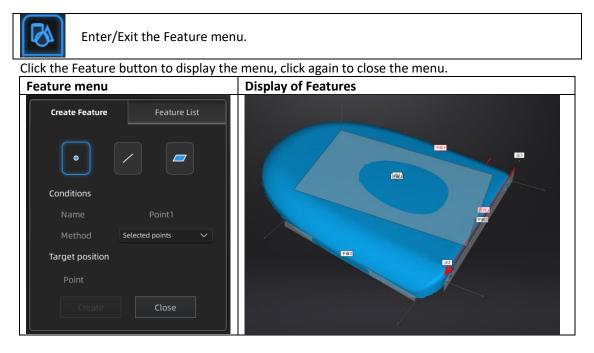
10. Measurement

After meshing, the Measurement menu will be available on the top. Or click Measurement on the navigation bar, and import data.



Click **Open file**, a STL or OBJ file can be imported to edit.

10.3.1. Create Feature



Click on the corresponding icon to create points, lines, planes.

Then select the creation method and follow the instructions, click "Create" to generate, or "Close" to cancel and close the window.

The features created displaying in gray, the selected feature is in Red. In the feature list, click "delete button" to remove (Delete action cannot undo).

Feature	Creation Method	Requi	irement Description		
	Selected Points			 Click on the data to select a point. 	
Point	Selected Politis			 Click create to create a point. 	
•	Line-Plane	Line	and	• Click on the created line, or select it on	the
	Interface	Plane	should	dropdown.	

		be created in	• Click on the created plane, or select it on
		advanced	the dropdown.
			The point generated is the intersection
			between the non-parallel line and plane.
			Feature creation failed! Error code 9: the line is
			parallel to the plane.
			 Pick 2 points.
			 Click on the data to select a point or click
			on a feature point previously created.
	Point-Point	—	In the Choice list select one of the point to redo
			it.
			The line generated is define as point from to
Line			point to point.
			 Click on the plane previously created, or
			select it on the dropdown, repeat for the
		2 Planes	second plane.
	Plane-Plane	should be	 The created line is the intersection
	Intersection	created in	between the 2 non-parallel planes.
		advanced	Feature creation failed! Error code 1: the
			planes are parallel.
			 The plane is generated by 3 points not
	3 Points Fit		co-linear.
			 Click on the data to select one point or
			click on a previous created feature point.
		—	 In the Choice list select one of the point to
			reselect it.
			Feature creation failed! Error code 6= the
			points selected are co-linear.
			 The plane generated includes the point
			and the line (The line should be created in
Plane			advanced).
		lino chould	 Click on the line previously created, or coloct it from the dron down
	Doint Line 5t	Line should	select it from the drop-down.
	Point-Line Fit	be created in	 Click on the data to select a point or click
		advanced	on a feature point previously created.
			• In the Choice list select one of the element
			to reselect it.
			Feature creation failed! Error code 6= the
			point selected belongs to the line
			• Press Shift+ LMB to select an area, press
			ctrl+ LMB to unselect.
	Best Fit	—	• The plane generated is the position with
			the smallest deviation from the selected
			area.

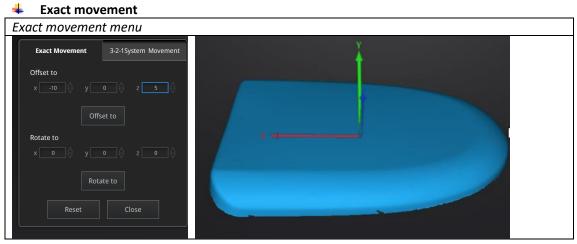
10.3.2. Movement

Use this mode to modify the alignment of the data to the global coordinate. This action is useful for post processing or reverse engineering.

The transformations do not affect the shape and size.

Enter/Exit the Movement menu.

Click the Movement button to display the menu, click again to close the menu.



Enter the value in mm and degrees, click **Apply** to match the data origin to the input coordinate and orientation.

The arrows represent the global coordinate system, Red=X+, Green=Y+, Blue=Z+.

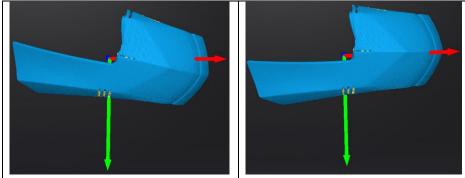
 $\label{eq:click} \textbf{Reset} \text{ to cancel the transformation to original position}.$

Click $\ensuremath{\textbf{OK}}$ to confirm the transformation.

Tips:

 \oplus

- Start from data reposition (offset to 0,0,0)
- Edit rotations prior to transformation
- Change the view normal to a reference plane to change the corresponding angle



4 3-2-1 Movement

Prior to 3-2-1 movement, the creation of a plane, line not normal to the plane and point are required.

3-2-1 movement (plane-line-point alignment) aligns the data by deletion of the Degrees of Freedom.

The arrows represent the global coordinate system, Red=X+, Green=Y+, Blue=Z+.

3-2-1 Movement menu

Exa	ict Movement	3-2-1System M	lovement	
Metho	d			Hit
Plane	plane2 🗸 🗸	Method	X+ 🗸	
Line	Constraint Line 🗸	Method S	elect 🗸	plane2
Point	Constraint Point 🗸			
	Align Re	set Cl	ose	

- Select a Plane in the drop-down menu, match it to the first axis in the Method drop-down. The arrows on the corners of the plane represent the plane positive direction. The normal vector of the plane will match the axis direction.
- Select a Line in the drop-down menu, match it to the first axis in the Method drop-down. Beware the direction of the line to match it to the + or - axis. The projection of the line to the first plane will be parallel to the corresponding axis.
- Select a Point in the drop-down menu. The data will be translated to match the point with the origin point (coordinate 0,0,0).

Click Align to perform the transformation.

Data after 3-2-1 movement

ict Movemer	nt	3-2-1System	Move	ement
d				
plane2	\sim	Method	X+	\sim
line1	\sim	Method	Y-	\sim
point1	~			
Alian	Res	et	Close	
	d plane2 line1	plane2 × line1 × point1 ×	d plane2 V Method line1 V Method point1 V	d plane2 V Method X+ line1 V Method Y- point1 V

Click Reset to cancel.

Click **Apply** to confirm the transformation.

10.3.3. Measuring

Click measurement button to display the menu, click again to close the menu.

DISTANCE

This tool calculates the distance between two points belonging to the surface of the data. Click on the data to pick the first and second point, select one of the two points to redo it. Distance menu

Dis	tance	Surface Area					
Sel	ect Poin	t					
۲	First P	oint					
	X: 5.219	545 Y: 136.767	517 Z: -114.955505				
0	Second	l Point					
	X: 3.114	550 Y: 65.8862	30 Z: 92.896904				
Dis	tance:						
	Total: 219.616074 mm						
	X: 2.104995						
	Y: 70.881287						
	Z: -207.	852409					
		Close					

Total is the 3D distance, X, Y and Z are the projection of the segment to the respective planes.

SURFACE AREA

Press Shift+ LMB to select an area, press ctrl + LMB to unselect.

Ctrl + A to select all.

Click **Calculate** to display the Area value of the selected data in mm² Redo the selection and click calculate again to update.

Surface	area	menu

Distance	Surface Area	Volume	
Surface Are	a		
Area: 9,02			
Calc	ulate Clos	e	

VOLUME

This tool calculates the volume contains in a watertight mesh.

It returns the volume in mm³ and the coordinates of the smallest box, parallel to the global coordinates, containing all the data.

	Volume menu	
Distance	Surface Area	Volume
Volume		
Total:	525,260.812500 n	nm³
Bounding l	хос	
X: -44.	0437, 194.8873	
Y: 48.5	5108, 247.9108	
Z: 324	.3329, 617.0605	
	Close	

Prior to the calculation make sure the file is watertight (no holes). File not watertight alert

Warning	
Please make it watertight	
ОК	

11. Export Data

11.1. Data Formats

Click to export the data. Navigate to choose a save folder. And input the file name. Select one of the formats below. By default, the saving path is the project folder, the file name is "Scan data", and the format is .stl.

	Save folder	
File name:	Scan data	Save
Files of type:	All Files (*) -	Cancel
□.	asc(whole) 🗹.stl 🗌.ply 🗌.obj 🗌.p3 🔲.3mf	

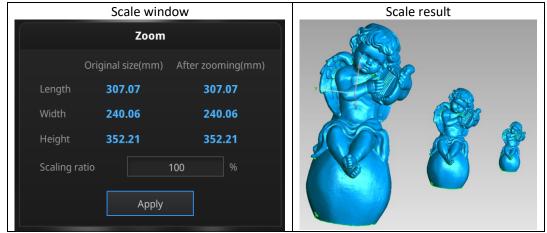
Format	Texture	Data type	Saves as	Recommended For
ASC (separated) (fixed mode only)	No	Separated point-clouds, with calculated alignment	scan_0.asc scan_1.asc scan_2.asc etc	 Inspection Fast export (no post-processing needed) Complex data to post process in another software
ASC (whole)	No	optimized point-cloud	scan.asc	 Inspection Fast export (no post-processing needed in hand-held mode) Large data to post process in another software Complex data to post process in another software
STL	No	Mesh	scan.stl	 3D printing (watertight mesh data) Reverse Engineering Compatibility with most mesh editing software
ОВЈ	Yes (separate d)	Mesh, Texture & Matching file	scan.obj scan.jpg scan.mtl	 Artistic applications 3D rendering Compatibility with most mesh editing software
PLY	Yes	Mesh	scan.ply	Low storageEasy texture editing
3MF	Yes	Mesh	scan.3mf	 Low storage Compatibility with Microsoft paint3d
Р3	No	Marker position	scan.p3	 Global Marker File in EinScan software Measurement of the marker

11.2. Scale Data

Scaling the volume of scanned data, while the number of triangles, the level of detail of the scan and size of data will not be actually changed.

By default, the scale is 100% and will be exported with millimeters for reference.

The value display represents the dimensions of the smallest box containing the data oriented to the reference axis.



12. Share Data

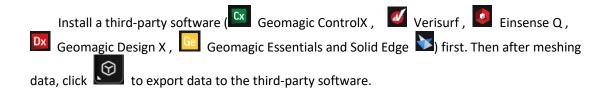
Click after mesh to share data to Sketchfab, it will show the dialog as below. A model title, username and user password are required. Register and view the shared model at http://sketchfab.com.

Note:

- Sketchfab basic plan accounts can only upload data less than 50M, while Pro plan account can share with a maximum of 200M.
- Data is saved as .STL does NOT contain texture.

Sketchfab Upload				
Share the current model to Sketchfab.com. All fields marked with an * are mandatory. Click here to register a free Sketchfab account.				
Model Title: *	EinScan HX			
Description:				
Tags (separated by space):	EinScan HX			
Make models private:	PRO account required			
Password:				
Sketchfab username:*				
Sketchfab password:*				
Submit Moo	del Cancel			

13. Third-party Software



14. Model Preview

Double click the short-cut

on the desktop. Drag files into the

window for preview. Manipulate the data with the same control as EXScan software.



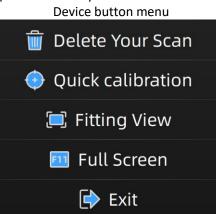
STL, OBJ, PLY, ASC, or 3MF can be loaded, files from 3rd party software might fail to be loaded. In this case we recommend Meshlab, a free mesh software editor, or upload to sketchfab.

Note:

To load a OBJ textured file make sure to have the MTL and JPG files with the same name and in the same folder than the OBJ.

15. Device Button

Long press the scan button on the device to pop up menu. You could then enter calibration, delete data, and full screen operation directly.



16. Support and Contact

16.1. Submit a Ticket

Sign up in Shining 3D Support Platform support.shining3d.com. Or send email directly to einscan support@shining3d.com.

Login to the support portal	or login using	Sign up
Enter the details below	G GOOGLE	SIGN UP WITH US
Your e-mail address	FACEBOOK	Once you sign up, you will have complete access to our self service portal and you o
Password	W TWITTER	use your account to raise support tickets and track their status.
Remember me on this computer		
Forgot your password?		

Log in with your account. Click New Ticket on the tab bar to submit a ticket and check the status.

How can we help you today?				
Enter your search term here	Q			
+ New Support Ticket Check Ticket Status				

16.2. Contact Us

By email einscan_support@shining3d.com sales@shining3d.com

Facebook Group: EinScanexpert

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